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PCTL model checking

Calculation example

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Reasoning about Time and Reliability Probabilistic CTL model checking

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13. Juli 2007 Seminar "Theorie und Anwendung von Model Checking"

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Motivati	on			

- Communication networks need to be error free and reliable. In addition, they often operate under real time conditions, meaning they must meet certain deadlines in order to work correctly.
- Particularly, this becomes vital when wireless networks are used – where significant packet loss is inevitable.
- In this talk, a temporal logic will be presented in which propositions such as "There is a probability of at least 99% that a message is received at most 6*ms* after it is sent." can be expressed.

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Summary

An extension to CTL with time and probability

- Probabilistic real time CTL (PCTL) is an extension to the well-known temporal logic CTL (Computation Tree Logic).
- PCTL extends this concept by both a discrete time structure allowing real time statements as well as probabilities for these events by which hard and soft deadlines can be modeled.
- There exist polynomial time model checking algorithms suitable for small structures.

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Syntax

Definition

- Atomic propositions are state formulae.
- If φ and ψ are state formulae, then so are ¬φ, (φ ∧ ψ),
 (φ ∨ ψ) and (φ → ψ).
- If φ and ψ are state formulae and $\tau \in \mathbb{N} \cup \infty$, then $(\varphi \operatorname{U}^{\leq \tau} \psi)$ and $(\varphi \operatorname{W}^{\leq \tau} \psi)$ are path formulae.
- If *F* is a path formula and ρ ∈ [0, 1], then [*F*]_{≥ρ} and [*F*]_{>ρ} are state formulae.

We will use $\varphi \operatorname{U}_{\geq \rho}^{\leq \tau} \psi$ as shorthand for $[\varphi \operatorname{U}^{\leq \tau} \varphi]_{\geq \rho}$.

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PCTL: some intuition

• $\varphi \operatorname{U}_{\geq 0.99}^{\leq 4} \psi$ means there is a probability of at least 99% that both ψ will come true within 4 time units and φ holds till ψ comes true.

- $\varphi W_{\geq 0.99}^{\leq 4} \psi$ means there is a probability of at least 99% that either the above condition holds or φ holds for at least 4 time units.
- If the underlying structure is modelled wisely, "time units" can be substituted with real time units such as "seconds" or "milliseconds".

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Summary

Expressing CTL through PCTL

Example

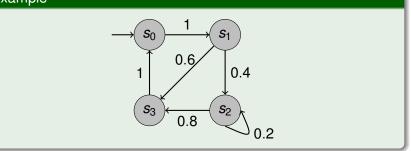
Since PCTL extends CTL, its properties can be expressed by extreme values of time and probability.

- generally: $\mathbf{G}\varphi \equiv \varphi \mathbf{W}^{\leq \infty}$ false
- finally: $\mathbf{F}\varphi \equiv \textit{true } \mathbf{U}^{\leq \infty} \varphi$
- until operator: $\varphi U \psi \equiv \varphi U^{\leq \infty} \psi$
- universal path quantifier: $\forall F \equiv [F]_{\geq 1}$
- existential path quantifier: $\exists F \equiv [F]_{>0}$

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Logic s	tructure			

The structure over which PCTL formulae are evaluated is a finite automaton with labels on states and probabilistic transitions. Each transition corresponds to one time step.

Example



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Summary

Formal definition of the structure

Definition

A structure \mathcal{K} is a tuple $(\mathcal{S}, \boldsymbol{s}_{\perp}, \mathcal{T}, \boldsymbol{L})$ where

- S is a finite set of states,
- $s_{\perp} \in S$ is the initial state,
- *T* is a probabilistic transition function *T* : S² → [0, 1], such that ∑_{t∈S} *T*(*s*, *t*) = 1 for all states *s* ∈ S and
- L is a labeling function assigning sets of atomic formulae to states (L : S → 2^{atom}).

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Summary

Prerequisites for semantics

Definition

- A path beginning in state s_0 is an infinite sequence $(s_0, s_1, ...)$. Let the set of paths (beginning in s_0) be $\mathcal{P}(s_0)$.
- The *n*-th state of a path π is denoted π[n], a finite prefix of length n is denoted π|_n := (s₀,...,π[n]).
- Solution For each state *s* a probability measure µ_s : P → [0, 1] is defined for each finite sequence (s₀,..., s_n) by

$$\mu_{s}(\{\pi \in \mathcal{P} : \pi|_{n} = (s_{0}, \ldots, s_{n})\}) = \prod_{i=1}^{n} \mathcal{T}(s_{i-1}, s_{i})$$

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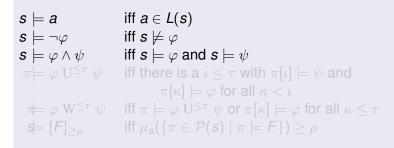
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Summary

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Definition



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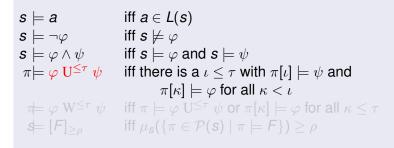
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Summary

Semantics

Definition



Semantics

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 $\begin{array}{ll} s \models a & \text{iff } a \in L(s) \\ s \models \neg \varphi & \text{iff } s \not\models \varphi \\ s \models \varphi \land \psi & \text{iff } s \models \varphi \text{ and } s \models \psi \\ \pi \models \varphi \operatorname{U}^{\leq \tau} \psi & \text{iff there is } a \iota \leq \tau \text{ with } \pi[\iota] \models \psi \text{ and} \\ \pi[\kappa] \models \varphi \text{ for all } \kappa < \iota \\ \pi \models \varphi \operatorname{W}^{\leq \tau} \psi & \text{iff } \pi \models \varphi \operatorname{U}^{\leq \tau} \psi \text{ or } \pi[\kappa] \models \varphi \text{ for all } \kappa \leq \tau \\ s \models [F]_{\geq \rho} & \text{iff } \mu_s(\{\pi \in \mathcal{P}(s) \mid \pi \models F\}) \geq \rho \end{array}$

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A model checking algorithm for PCTL

- In this section a model checking algorithm will be presented, which determines whether a given structure *K* models some formula φ, i.e. ⊨_K φ.
- When it finishes, each state will be labeled with the complete set of subformulae of φ which hold in that state. If the initial state s_⊥ is labeled with φ, then the structure is a model for φ.
- The algorithm is based on the original model checking algorithm for CTL.

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- The algorithm is based on the original model checking algorithm for CTL.

- We define an extended labeling function *L* for every subformula of *φ*. Initially, all states are labeled with atomic propositions: ∀*s* ∈ *S* : *L*(*s*) := *L*(*s*)
- ⁽²⁾ Suppose the subformulae of φ have been ordered in size (of logic connectives). Then from the smallest to φ itself change the labels of all states:
 - For a subformula $\neg \psi$ set $\mathcal{L}(s) := \mathcal{L}(s) \cup \{\neg \psi\}$ if $\psi \notin \mathcal{L}(s)$
 - For a subformula $(\varphi_1 \land \varphi_2)$ set $\mathcal{L}(s) := \mathcal{L}(s) \cup \{\varphi_1 \land \varphi_2\}$ if $\varphi_1, \varphi_2 \in \mathcal{L}(s)$.
 - For a subformula (φ₁ U^{≤τ}_{≥ρ} φ₂) use the following algorithm based on matrix multiplication.

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 - For a subformula $(\varphi_1 \cup_{\geq \rho}^{\leq \tau} \varphi_2)$ use the following algorithm based on matrix multiplication.



Assume $\tau < \infty$. Let s_1, \ldots, s_n be the states of S.

• Define a $n \times n$ transition matrix $A = (\alpha_{ij})$ by

$$\alpha_{ij} = \begin{cases} \mathcal{T}(\boldsymbol{s}_i, \boldsymbol{s}_j) & \text{if } \varphi_1 \in \mathcal{L}(\boldsymbol{s}_i) \text{ and } \varphi_2 \notin \mathcal{L}(\boldsymbol{s}_i) \\ 1 & \text{else if } i = j \\ 0 & \text{otherwise} \end{cases}$$

By this, some transition probabilities are given: Rows represent the "from-states" and columns represent the "to-states".

 Thus, the matrix A^τ intuitively gives transition probabilities for τ transition steps.



• Define a vector $P = (p_k)$ of size *n* with

$$p_k = egin{cases} 1 & ext{if } arphi_2 \in \mathcal{L}(m{s}_k) \ 0 & ext{otherwise} \end{cases}$$

Intuitively, this represents the set of states in which φ_2 (the postcondition) is true.

- Calculate the vector P' := A^τ · P. This represents the probabilities of each state modeling the until-formula.
- Thus, for each state s_k redefine L(s_k) :=
 L(s_k) ∪ {φ₁ U^{≤τ}_{≥ρ} φ₂} if the k-th entry in P' is at least ρ.



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Labeling in special cases

- The case with $\tau = \infty$ must be treated separately.
- Other extreme cases can be calculated with separate algorithms for optimization reasons.
- The weak until operator W can be transformed into a formula with just U.
- There is another algorithm for calculation of P' with slightly different complexity.

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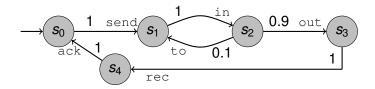




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Verification of a communication protocol

As an example, we will now verify a simple (fictional) communication protocol. It provides error free communication from a sender to a receiver over a lossy medium. We assume that acknowledgements are never lost though.



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We also assume the message loss probability to be 10%.



- An interesting question to pose is, if the system is able to meet certain deadlines, for example if there is a probability of at least 99% that a message is received (s₄) at most 6 time units after it is send (s₀).
- For a single event, this can be expressed by



where F is a generalized finally-operator with time and probability.

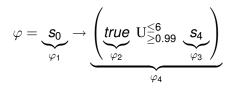
- An interesting question to pose is, if the system is able to meet certain deadlines, for example if there is a probability of at least 99% that a message is received (s₄) at most 6 time units after it is send (s₀).
- For a single event, this can be expressed by

$$s_0
ightarrow \mathrm{F}_{\geq 0.99}^{\leq 6} s_4$$

where F is a generalized finally-operator with time and probability.



 First of all, we translate the formula into a "pure until-formula" and name the subformulae:



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• Now states will labeled with atomic propositions:

- Label s_0 with φ_1 .
- Label every state with φ_2 .
- Label s_4 with φ_3 .



 First of all, we translate the formula into a "pure until-formula" and name the subformulae:

$$\varphi = \underbrace{\mathbf{s}_{0}}_{\varphi_{1}} \rightarrow \underbrace{\left(\underbrace{\textit{true}}_{\varphi_{2}} \ \mathbf{U}_{\geq 0.99}^{\leq 6} \ \underbrace{\mathbf{s}_{4}}_{\varphi_{3}}\right)}_{\varphi_{4}}$$

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- Now states will labeled with atomic propositions:
 - Label s₀ with φ₁.
 - Label every state with φ₂.
 - Label s₄ with φ₃.

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Summary

Construction of matrix A and vector P

We construct the matrix *A* and the vector *P* according to the definition given earlier:

$$A = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0.1 & 0 & 0.9 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \qquad P = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

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Labeling for $\varphi_4 = \varphi_2 \operatorname{U}_{\geq 0.99}^{\leq 6} \varphi_3$

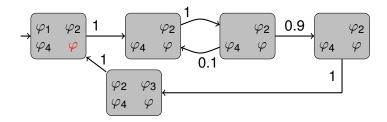
Next, we calculate $P' = A^6 \cdot P$:

$$A^{6} = \begin{pmatrix} 0 & 0 & 0.01 & 0 & 0.99 \\ 0 & 0.001 & 0 & 0.009 & 0.99 \\ 0 & 0 & 0.01 & 0 & 0.99 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix} \qquad P' = \begin{pmatrix} 0.99 \\ 0.99 \\ 0.99 \\ 1 \\ 1 \end{pmatrix}$$

Since every entry in P' is at least 0.99, we conclude that every state is to be labeled with φ_4 .

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Finally, every state is labeled with $\varphi = (\varphi_1 \rightarrow \varphi_4)$ since every state is labeled with φ_4 .



Since the initial state s_0 is labeled with φ , we have shown that the given protocol is a model for our assumption.

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Summa	ary			

- The motivation for a logic like PCTL stems largely from an application view.
- We have seen practical usefulness for PCTL-expressible properties.
- The model checking algorithm shown is implemented in the PRISM model checking tool.
- H. Hansson and B. Jonsson.

A logic for reasoning about time and reliability. Technical Report R90013, Swedish Institute of Computer Science and Department of Computer Systems, Uppsala University, Dec. 1994.